

## Vectors and Vector Spaces

A **vector** in an abstract  $N$ -dimensional space can be represented by a set of numbers (components):  $\mathbf{a} = (a_1, a_2, a_3, \dots, a_N)$

Example: in Cartesian 3-dimensional space:  $\vec{a} = (a_x, a_y, a_z) = a_x \hat{i} + a_y \hat{j} + a_z \hat{k}$  where the  $\hat{i}, \hat{j}, \hat{k}$  are orthogonal vectors of unit length in the  $x$ -,  $y$ -, and  $z$ -directions, respectively.

### Vector Space

A set of vectors  $\mathbf{a}, \mathbf{b}, \mathbf{c}, \mathbf{d}, \dots$  forms a **vector space** if

(i) they obey commutative and associative rules of addition:

$$\begin{aligned} \mathbf{a} + \mathbf{b} &= \mathbf{b} + \mathbf{a} \quad \text{is a vector in the same space} \\ (\mathbf{a} + \mathbf{b}) + \mathbf{c} &= \mathbf{a} + (\mathbf{b} + \mathbf{c}) \end{aligned}$$

(ii) they can be multiplied by scalars to produce a new vector in the space:

$$\begin{aligned} \lambda \mathbf{a} &\text{ is a new vector in the space} \\ \lambda(\mathbf{a} + \mathbf{b}) &= \lambda \mathbf{a} + \lambda \mathbf{b} \\ (\lambda + \mu)\mathbf{a} &= \lambda \mathbf{a} + \mu \mathbf{a} \\ \lambda(\mu \mathbf{a}) &= (\lambda\mu)\mathbf{a} \end{aligned}$$

(iii) there exists a null vector  $\mathbf{0}$  such that  $\mathbf{a} + \mathbf{0} = \mathbf{a}$  for all  $\mathbf{a}$

(iv) multiplication by unity leaves any vector unchanged,  $\mathbf{1} \times \mathbf{a} = \mathbf{a}$

(v) all vectors have a negative  $-\mathbf{a}$  such that  $\mathbf{a} + (-\mathbf{a}) = \mathbf{0}$ .

### Linear independence

A member of a set of **linearly independent** vectors cannot be expressed as a linear sum of other vectors in the set. For example, in the set of Cartesian unit vectors  $\hat{i}, \hat{j}, \hat{k}$ , the unit vector  $\hat{i}$  cannot be expressed as a sum  $\hat{i} = c_1 \hat{j} + c_2 \hat{k}$  for any coefficients  $c_1$  and  $c_2$ .

## Basis Vectors

A set of linearly independent vectors  $\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3, \dots, \mathbf{e}_N$  forms a **basis** if any other vector in the space can be expressed as a linear sum  $\mathbf{a} = \sum_{i=1}^N a_i \mathbf{e}_i$  where the  $a_i$  are scalar coefficients (components).

Note: the coefficients relate to a particular basis. In another basis set  $\mathbf{e}'_1, \mathbf{e}'_2, \mathbf{e}'_3, \dots, \mathbf{e}'_N$ ,

$$\mathbf{a} = \sum_{i=1}^N a'_i \mathbf{e}'_i \text{ where the } a'_i \neq a_i \text{ for at least some } i.$$

## Inner Product

Two vectors  $\mathbf{a}$  and  $\mathbf{b}$  in a vector space can form an **inner product**  $\langle \mathbf{a} | \mathbf{b} \rangle$ , which is a scalar function.

If the vectors are complex (have complex components), then  $\langle \mathbf{a} | \mathbf{b} \rangle = \langle \mathbf{b} | \mathbf{a} \rangle^*$ .

$$\text{Also, } \langle \lambda \mathbf{a} + \mu \mathbf{b} | \mathbf{c} \rangle = \lambda^* \langle \mathbf{a} | \mathbf{c} \rangle + \mu^* \langle \mathbf{b} | \mathbf{c} \rangle \quad \text{and} \quad \langle \lambda \mathbf{a} | \mu \mathbf{b} \rangle = \lambda^* \mu \langle \mathbf{a} | \mathbf{b} \rangle.$$

If  $\mathbf{a}$  and  $\mathbf{b}$  are **orthogonal** to one another,  $\langle \mathbf{a} | \mathbf{b} \rangle = 0$ .

The **norm** of a vector  $\mathbf{a}$  is  $\|\mathbf{a}\| = \langle \mathbf{a} | \mathbf{a} \rangle^{1/2}$ .

If the vectors  $\hat{\mathbf{e}}_1, \hat{\mathbf{e}}_2, \hat{\mathbf{e}}_3, \dots, \hat{\mathbf{e}}_N$  of a basis set are orthogonal and have norm = 1, i.e. if  $\langle \hat{\mathbf{e}}_i | \hat{\mathbf{e}}_j \rangle = \delta_{ij}$ , the set is **orthonormal** ( $\delta_{ij} = 0$  if  $i \neq j$ ,  $\delta_{ij} = 1$  if  $i = j$ ).

**Projection** of vector  $\mathbf{a}$  on to basis vector  $\hat{\mathbf{e}}_j$ :  $\langle \hat{\mathbf{e}}_j | \mathbf{a} \rangle = a_j$  (orthonormal basis).

$$\text{If } \mathbf{a} = \sum_{i=1}^N a_i \hat{\mathbf{e}}_i \quad \text{and} \quad \mathbf{b} = \sum_{i=1}^N b_i \hat{\mathbf{e}}_i, \quad \text{then} \quad \langle \mathbf{a} | \mathbf{b} \rangle = \sum_{i=1}^N a_i^* b_i \quad (\text{orthonormal basis}).$$

In ordinary 3-dimensional space, the inner product is the **dot product**:  
 $\langle \mathbf{a} | \mathbf{b} \rangle = \bar{\mathbf{a}} \cdot \bar{\mathbf{b}} = |\bar{\mathbf{a}}| |\bar{\mathbf{b}}| \cos \theta_{ab}$ .

**Inequalities involving inner products and norms**

(i) Schwartz's inequality:  $|\langle \mathbf{a} | \mathbf{b} \rangle| \leq \|\mathbf{a}\| \|\mathbf{b}\|$ , equal if  $\mathbf{a} = \lambda \mathbf{b}$ .

(ii) Triangle inequality:  $\|\mathbf{a} + \mathbf{b}\| \leq \|\mathbf{a}\| + \|\mathbf{b}\|$ .

(iii) Bessel's inequality:  $\langle \mathbf{a} | \mathbf{b} \rangle \geq \sum_{i=1}^M |a_i|^2$ , equal if  $M = N$  (dimension of space).

(iv) Parallelogram equality:  $\|\mathbf{a} + \mathbf{b}\|^2 + \|\mathbf{a} - \mathbf{b}\|^2 = 2(\|\mathbf{a}\|^2 + \|\mathbf{b}\|^2)$ .